

Statistical identification of orographic effects in the regional  
analysis of extreme rainfall

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8 *Abstract*

9 Regional models of extreme rainfall must address the spatial variability induced by  
10 orographic obstacles. However, the proper detection of orographic effects often depends  
11 on the availability of a well-designed rain gauge network. The aim of this study is to  
12 investigate a new method for identifying and characterizing the effects of orography on  
13 the spatial structure of extreme rainfall at the regional scale, including where rainfall data  
14 are lacking or fail to describe rainfall features thoroughly.

15 We analyze the annual maxima of daily rainfall data in the Campania region, an  
16 orographically complex region in Southern Italy, and introduce a statistical procedure to  
17 identify spatial outliers in a low order statistic (namely the mean). The locations of these  
18 outliers are then compared to a pattern of orographic objects that has been *a priori*  
19 identified through the application of an automatic geomorphological procedure. The  
20 results show a direct and clear link between a particular set of orographic objects and a  
21 local increase in the spatial variability of extreme rainfall. This analysis allowed us to  
22 objectively identify areas where orography produces enhanced variability in extreme  
23 rainfall. It has direct implications for rain gauge network design criteria and has led to  
24 promising developments in the regional analysis of extreme rainfall.

25

26 Keywords: regional analysis; extreme rainfall; Kriging with uncertain data; orographic  
27 barriers.

28 **1. Introduction**

29 The regional analysis of extreme rainfall has to deal with the spatial variability of the  
30 rainfall process, which is driven by many physical factors, particularly those related to  
31 regional topography and its complex interactions with atmospheric circulation.

32 In the field of Earth and atmospheric sciences, physical modeling of atmospheric  
33 processes driven by orography at the event scale has long been a challenging problem  
34 (Smith, 1979; Rotunno and Ferretti, 2001; Roe, 2005 among the others). In recent years,  
35 major advances in meteorological modeling have been achieved, supported by the  
36 increasing availability of high-resolution data from remote sensors. These improvements  
37 have led to better real-time forecasting systems, especially through the introduction of  
38 very sophisticated, three-dimensional, non-hydrostatic models of atmospheric dynamics  
39 (Grell et al., 1995; Rotunno and Houze, 2007; Malguzzi et al., 2006).

40 Long-term probabilistic predictions of extreme rainfall at regional scale present a  
41 different problem. These predictions are primarily based on statistical analyses of extreme  
42 rainfall time series recorded by a network of rain gauges at the regional scale. In this case,  
43 one of the main issues is to identify and model the effects of orography on particular  
44 statistical parameters identified for rainfall extremes. Physically based models of single  
45 storms are not sufficient for this task: Statistical parameters associated with annual  
46 rainfall maxima are affected by a multitude of events that have different characteristics.  
47 As a result, the final impact on these parameters is difficult to predict. To better describe  
48 how orography influences these parameters, orographic data must be embedded into a  
49 regional model of extreme rainfall.

50 The typical regionalization approach, which is based on the application of regression  
51 relationships within homogeneous regions (Matalas and Gilroy, 1968), usually makes use

52 of local descriptors of topography and tends to over-simplify the complex effects of  
53 orography on extreme rainfall (among others, Poreh and Mechrez, 1984; Corradini, 1985;  
54 Givone and Meignen, 1990; Weisse and Bois, 2001; Roe, 2005). As a result, regression  
55 errors are often spatially correlated, suggesting that a regression model alone cannot  
56 provide a satisfactory interpretation of the spatial variability of the field. A common  
57 solution to this problem is to split the region into smaller, more homogeneous sub-  
58 regions, or to couple a regression model with a spatial, non-parametric model of the  
59 residuals. The spatial model is usually based on the assumption of an intrinsically  
60 stationary random field: linear geostatistics provides BLUE (Best Linear Unbiased  
61 Estimator) estimators for this type of field. In addition, a geostatistical approach provides  
62 tools for evaluating the interpolation uncertainty related to network density and allows  
63 researchers to define the optimal criteria for network design (among others, Rodriguez-  
64 Iturbe and Meja, 1974; Bras and Rodriguez-Iturbe, 1976; Bacchi and Kottegoda, 1995;  
65 Bacchi, 1996; Pardo-Igúzquiza, 1998).

66 The approach of coupling a regression model with a spatial, non-parametric model of the  
67 residuals aims at describing the general dependence of rainfall on site-based topographic  
68 indices and capturing the complex interactions of rainfall with orography using spatial  
69 interpolation techniques. It can indeed give adequate results for technical purposes, but  
70 only if the spatial field is stationary and if a sufficiently dense rain gauge network is  
71 available. To improve the predictive ability of the regional models, increasingly  
72 sophisticated regression and spatial interpolation models have been introduced. The  
73 primary goal of these efforts is to add topographic covariates into the models, through the  
74 definition of features at the site level that are synthetic descriptors of topography at a  
75 broader scale (Slimani and Obled, 1986; Prudhomme and Reed, 1999; Weisse and Bois,

76 2001; Allamano et al., 2009). Thus, significant advances in regional modeling accuracy  
77 have been reached with a relatively moderate increase in the number of model parameters.  
78 Another way to improve regional models of extreme rainfall is to approach the description  
79 of a site's orography in new ways. For example, identification and characterization of the  
80 most relevant orographic features in a region can be used instead of relying on local or  
81 locally averaged descriptors of the topography obtained from the DEM (Digital Elevation  
82 Model). A recent paper from Cuomo et al. (2011) introduced a GIS-based, objective  
83 geomorphological procedure to identify and characterize orographic objects from a DEM  
84 of topography. The results of this geomorphological procedure can provide new and  
85 potentially valuable information relevant to several traditional problems of applied  
86 hydrology. This study will investigate their potential applications in the regional analysis  
87 of extreme rainfall.

88 In this paper, we consider a relatively wide and orographically complex region in  
89 Southern Italy, the Campania region. Then, in Section 3, we introduce a statistical  
90 procedure to identify "anomalous" spatial variability in the mean annual maxima of daily  
91 rainfall (here, "anomalous" refers to the null hypothesis of the weak stationary nature of  
92 the spatial field at the regional scale). The procedure addresses the non-Gaussian  
93 distribution of the original data and the presence of heteroscedastic site-based sampling  
94 errors (generated by the variable length of the time series). Anomalous values are strongly  
95 suspected to be caused by amplifications in intense rainfall driven by orography. By  
96 comparing the locations of anomalous gauges, as identified using this statistical  
97 procedure, with independently identified orographic objects, we observed a relationship  
98 between a particular set of orographic objects and the increased spatial variability of the  
99 rainfall field at small scale. This suggests that the selected topographic elements might

100 effectively act as orographic barriers during rainfall events and may provide a key for  
101 interpreting observed amplifications in the spatial variability of extreme rainfall. This  
102 preliminary analysis provides some basic results that can be useful for improving the  
103 methods of rain gauge network analysis and design and building more accurate regional  
104 models of extreme rainfall.

105 In the next section, we present the study region, the hydrological dataset used for this  
106 study and a summary of the geomorphological identification of the orographic objects in  
107 the region. Section 3 contains a summary of the mathematical methods used in this paper,  
108 with a particular focus on the geostatistical techniques that are commonly used within  
109 regionalization studies. These methods provide the foundation for the statistical  
110 procedure presented in Section 4, along with the procedure's application to the case study,  
111 in which we identify anomalous spatial variability of the mean annual maxima of daily  
112 rainfall in the study region. In Section 5, we summarize and discuss the results by  
113 comparing the positions of the spatial outliers with the positions of the potential  
114 orographic barriers. Future work and potential applications of the results are discussed in  
115 the final section.

## 116 **2. Study area, rainfall data set and orographic descriptors**

117 The area selected for this study roughly corresponds to the Campania region in Southern  
118 Italy and includes some surrounding areas (Figure 1). Its complex orography interacts  
119 with wet air masses that come predominantly (but not exclusively) from the Tyrrhenian  
120 Sea and affects the spatial variability of many rainfall events. The current regional report  
121 on rainfall extremes in this area was prepared within the CNR's (Consiglio Nazionale  
122 delle Ricerche, National Research Council) VAPI (VALutazione delle PIene, Flood

123 Estimation) project (Versace et al., 1989; Rossi and Villani, 1995; 1998), a national  
124 project designed to analyze the frequency of extreme rainfall and river floods at a regional  
125 scale. The regionalization of the annual daily rainfall maxima is based on a TCEV (Two  
126 Component Extreme Value) parent distribution (Rossi et al., 1984). For dimensionless  
127 high order parameters (coefficients of variation, skewness and kurtosis), the hypothesis  
128 that the entire region is statistically homogeneous is accepted. The average of the annual  
129 daily rainfall maxima was regionalized by identifying 6 sub-regions based on an  
130 estimated linear regression associated with elevation. The large number of sub-regions  
131 suggests that the spatial variability of the lowest order statistics may be strongly  
132 influenced by an orographic pattern.

133 This work is based on annual daily rainfall maxima because they represent the most  
134 reliable and largely available data in the region. A summary of the characteristics of the  
135 time series for the dataset is presented in Table 1. Given the results of previous regional  
136 studies, we focused on the mean of the annual maxima, which shows significant spatial  
137 variability when compared with its statistical variability. A map of Central-Southern Italy  
138 is presented in Figure 1, along with the locations of the 605 rain gauges used for the  
139 analysis: 245 of them are located inside the actual region of interest, as shown in the same  
140 figure. We included a comfortable buffer on all edges of the region of interest to reduce  
141 accidental border effects. We used a rainfall database collected within the VAPI project  
142 ([http://www.gndci.cnr.it/it/vapi/welcome\\_it.htm](http://www.gndci.cnr.it/it/vapi/welcome_it.htm)). The database was updated after the  
143 publication of the regional report up to the year 2000.

144 The topography of the study area was modeled using a 20 m resolution DEM. Figure 1  
145 illustrates the presence of a relevant orographic barrier, the Apennines along the inner  
146 section of the peninsula, together with many other mountains that run between the

147 coastline and the Apennines. Cuomo et al. (2011) identify and classify mountains through  
148 an automatic and multi-scalar analysis of geomorphometric characteristics of the  
149 topography. The method is similar to well-known drainage network ordering systems and  
150 is based on the topographic concepts of key contour, key saddle, summit point and  
151 prominence (see Figure 2 for a summary of the method). The procedure is implemented  
152 in a GIS environment and is able to identify, delimit and order mountains and hills  
153 automatically. Simultaneously, the procedure finds the parent relationship between  
154 orographic entities and organizes the ordered mountains into an orographic hierarchy.  
155 In this work, the union of orographic ranges (4<sup>th</sup> order) and orographic groups (3<sup>rd</sup> order)  
156 is chosen as the set of orographic objects that affects the spatial variability of the annual  
157 daily rainfall maxima (Figure 3). Here, this choice is driven by a comparison with the  
158 results of the presented statistical analysis of the spatial variability of annual daily rainfall  
159 maxima. However, this observed result is worth deeper investigation, since it is surely  
160 related to the interaction between the typical scale of the orographic objects in space and  
161 elevation and the scales of the meteorological events that most frequently produce the  
162 annual maxima.

### 163 **3. Mathematical methods**

164 In this section, we describe well-known mathematical methods relevant to this study and  
165 to the procedure proposed in Section 4.

#### 166 *3.1. Geostatistical methods for data affected by noise*

167 An intrinsically stationary, isotropic random field  $Z(\mathbf{x})$  has a unique spatial structure that  
 168 can be expressed through the semi-variogram of the field (Cressie, 1993; Journel and  
 169 Huijbregts, 1978):

$$\gamma(d) = \frac{1}{2} E [Z(\mathbf{x} + \mathbf{d}) - Z(\mathbf{x})]^2; \quad (d = \|\mathbf{d}\|) \quad (1)$$

170 Given a set of measurements of the field  $\{Z_i^*; i = 1, \dots, n\}$  available at each site  
 171  $\{\mathbf{x}_i; i = 1, \dots, n\}$ , the semi-variogram  $\gamma(d)$  is estimated by fitting suitable parametric  
 172 analytic functions to the experimental semi-variogram (Kitadinis, 1983; Todini and  
 173 Pellegrini, 1999).

174 If the observed data  $Z_i^*$  are noise-free observations of the real values  $Z_i$ , the Ordinary  
 175 Kriging Predictor (OKP) is the optimal linear estimator, which is the best possible  
 176 estimator if the field is also Gaussian (Journel and Huijbregts, 1978). The Ordinary  
 177 Kriging system provides a set of weights  $\{w_i; i = 1, \dots, n\}$  that define the best (minimum  
 178 variance) unbiased linear estimator:

$$\hat{Z}_K(\mathbf{x}) = \sum_{i=1}^n w_i \cdot Z_i^* \quad (2)$$

179 The variance of the estimator is also known:

$$\sigma_K^2(\mathbf{x}) = 2 \cdot \sum_{j=1}^n w_j \cdot \gamma(\|\mathbf{x} - \mathbf{x}_j\|) - \sum_{k=1}^n \sum_{j=1}^n w_k w_j \cdot \gamma(\|\mathbf{x}_k - \mathbf{x}_j\|) \quad (3)$$

180 This feature makes the kriging estimator an appealing tool for network design  
 181 (Rodriguez-Iturbe and Meja, 1974; Bras and Rodriguez-Iturbe, 1976; Bacchi, 1996). In  
 182 fact, the variance in Equation (3) is solely a function of the geometry of the network and  
 183 the semi-variogram of the field.

184 The presence of additional noise in the observed field (measurement errors, sampling  
185 errors, etc.) affects the optimal nature of the Ordinary Kriging Predictor, although its  
186 impacts on the predictor's unconditional unbiasedness are minimal (Borgault, 1994;  
187 Furcolo and Villani, 1998). When spatial interpolation of the field is the only desired  
188 result, Ordinary Kriging often represents a quick and reasonably accurate predictor.  
189 However, when the distribution and variance of predictor residuals is of interest, the noise  
190 in the data can dramatically affect the results and, consequently, the geostatistical  
191 technique must be modified.

192 In the fairly general case of a field contaminated with heteroscedastic uncorrelated noise,  
193 an optimal variant of the OKP, the Kriging with Uncertain Data (de Marsily, 1986;  
194 Slimani and Obled, 1986; Mazzetti and Todini, 2009), can be defined. Here, we use the  
195 KUD system as derived by de Marsily (1986). The application of this estimator requires  
196 knowledge of the semi-variogram of the true (noiseless) field and the noise variance at  
197 each sampling site. These requirements, which appear fairly strong, are not unrealistic in  
198 many applications, particularly where the noise variance is known *a priori* and the 'true'  
199 semi-variogram can, as a result, be estimated from the experimental variogram.

200 Onsite noise is defined as:

$$\delta_i = \delta(\mathbf{x}_i) = Z_i^* - Z_i \quad (4)$$

201 where  $\{\delta_i; i = 1, \dots, n\}$  is a set of uncorrelated Gaussian noise with zero mean and variance  
202  $\sigma_i^2 = \text{Var}[\delta(\mathbf{x}_i)]$ . Given the semi-variogram of the noiseless field  $\gamma(d)$ , the Kriging  
203 with Uncertain Data system varies slightly from the Ordinary Kriging Predictor and is  
204 expressed as follows (de Marsily, 1986, p.300):

$$\begin{cases} \sum_{j=1}^n w_j \gamma(\|\mathbf{x}_i - \mathbf{x}_j\|) - w_i \sigma_i^2 + m = \gamma(\|\mathbf{x}_i - \mathbf{x}\|) & i = 1, \dots, n \\ \sum_{j=1}^n w_j = 1 \end{cases} \quad (5)$$

205 Here, the unknowns are the  $n$  weights  $\{w_i; i = 1, \dots, n\}$  and  $m$ , which is the Lagrange  
 206 multiplier for the unbiasedness constraint. The variance of the prediction error relative to  
 207 the noiseless field  $Z(\mathbf{x}) - \hat{Z}_K(\mathbf{x})$  becomes:

$$\sigma_K^2(\mathbf{x}) = 2 \cdot \sum_{j=1}^n w_j \cdot \gamma(\|\mathbf{x} - \mathbf{x}_j\|) - \sum_{k=1}^n \sum_{j=1}^n w_k w_j \cdot \gamma(\|\mathbf{x}_i - \mathbf{x}_j\|) + \sum_{j=1}^n w_j^2 \cdot \sigma_i^2 \quad (6)$$

208 Differently from the OKP, the exactness property does not hold for the KUD: the  
 209 predictor acts as a filter and does not produce the exact measured values at gauged sites.  
 210 As a result, the predictor variance at gauged sites is greater than zero. It is worth  
 211 remarking that the prediction error is related to the noiseless field. This implies that the  
 212 residuals at gauged sites  $Z_i^* - \hat{Z}_K(\mathbf{x}_i)$  have a larger variance ( $\sigma_K^{2*}$  in the next equation)  
 213 than the prediction error itself:

$$\sigma_K^{2*}(\mathbf{x}_i) = \text{Var}(Z_i^* - \hat{Z}_K(\mathbf{x}_i)) = \sigma_K^2(\mathbf{x}_i) + \sigma_i^2(1 - 2w_i) \quad (7)$$

214 When the spatial interpolation addresses a directly measurable physical quantity, onsite  
 215 noise is representative of the measurement errors and it is usually neglected without  
 216 relevant consequences for the result. However, if the field of a statistical parameter is  
 217 analyzed, the onsite noise is produced by sampling errors. The variance of sampling errors  
 218 depends on the length of the series, which in turn varies from site to site, producing  
 219 heteroscedasticity. Inter-station correlations, caused by rainfall events that produce an  
 220 annual maximum simultaneously at different gauges, can further complicate the picture,  
 221 because it may introduce a correlation structure in the noise field as well.

222 In this study, the presence of sampling errors in the data is explicitly considered using the  
 223 KUD estimator. We also analyzed all the couples of annual maxima time series and  
 224 calculated the amount of correlation that is due to the same rainfall events (by checking  
 225 the dates of the annual maxima). In this way we were able to assess the effect of inter-  
 226 station correlation, and it was found to be negligible. Therefore, it is assumed that the  
 227 sampling errors are heteroscedastic and uncorrelated.

### 228 3.2. Cross-validation and distribution of standardized residuals

229 Cross-validation is a method generally used to assess the performance of kriging  
 230 estimators. It is based on a jackknife kriging estimation of values at sampling sites using  
 231 only the values available from the other (n-1) sites:

$$\hat{Z}_{JN}(\mathbf{x}_i) = \hat{Z}_K(\mathbf{x}_i) \Big|_{\{Z_1^*, \dots, Z_{i-1}^*, Z_{i+1}^*, \dots, Z_n^*\}} \quad i = 1, \dots, n \quad (8)$$

232 For the OKP, the differences between the sampled (noise-free) and estimated values  
 233 represent the estimation errors. These random errors are expected to have a Gaussian  
 234 distribution, with zero mean and a variance that corresponds to the estimated predictor  
 235 variance  $\sigma_{JN}^2$ . They can be then standardized as follows:

$$e_i = \frac{Z_i^* - \hat{Z}_{JN}(\mathbf{x}_i)}{\sigma_{JN}(\mathbf{x}_i)} = \frac{Z(\mathbf{x}_i) - \hat{Z}_{JN}(\mathbf{x}_i)}{\sigma_{JN}(\mathbf{x}_i)} \quad (9)$$

236 Based on the hypotheses of the kriging predictor, the standardized errors should follow a  
 237 standard Gaussian distribution. They may still be affected by a small amount of spatial  
 238 correlation; however, this can be eliminated by using ortho-normal residuals (Kitadinis,  
 239 1993), though these are less objectively defined. It is common for standardized errors to  
 240 show little or no correlation structure, as is the case in this study. Given this, the present

241 study uses simple and objectively defined standardized errors instead of ortho-normal  
 242 errors.

243 When onsite sampling variance is introduced and kriging is used as a filter (KUD), the  
 244 jackknife residuals are the sum of the kriging errors and the data errors. Yet, if the data  
 245 errors are as defined in Equation (4) and the basic kriging hypotheses still hold, these  
 246 residuals can be standardized using the variance in Equation (7), with  $w_i = 0$  (because it  
 247 is a jackknife estimation):

$$e_i^* = \frac{Z_i^* - \hat{Z}_{JN}(\mathbf{x}_i)}{\sigma_{JN}^*(\mathbf{x}_i)} \quad (10)$$

248 The standardized residuals  $\{e_i^*\}$  are expected to be distributed according to a  
 249 standardized normal distribution as well. The observed frequency distribution of the  
 250 standardized residuals is estimated through the Weibull plotting position  $P_k = k / (n + 1)$   
 251 and compared with the expected normal distribution. Here,  $k$  is the position of a datum  
 252 in the ordered sample  $\{\varepsilon_k = e_{\pi_n(k)}^*; \varepsilon_k \geq \varepsilon_{k-1}\}$  as defined through a permutation  $\pi_n(k)$  of  
 253 the indices in the interval  $\{1, \dots, n\}$ . For a given datum in the sample, the Weibull plotting  
 254 position actually represents the expected value of the non-exceedance probability, whose  
 255 distribution is in turn known to be a beta distribution with parameters  $a = k$  and  
 256  $b = n - k + 1$ :

$$f_{P_k}(p) = \frac{p^a \cdot (1-p)^b}{B(a,b)} = \frac{\Gamma(a+b) \cdot p^a \cdot (1-p)^b}{\Gamma(a) \cdot \Gamma(b)} \quad (11)$$

257 When plotted on a Normal Probability Chart, the empirical points represented by the pairs  
 258  $(\varepsilon_k, P_k)$  are supposed to organize with a good approximation along a straight line  
 259 corresponding to a Gaussian CDF (Cumulative Distribution Function). It is possible to

260 test the actual agreement between the observations and the theoretical model by defining  
261 confidence intervals around the plotting positions, according to the beta distribution in  
262 Equation (11).

263 This approach provides the basis for the identification of spatially anomalous values that  
264 will be carried out in Section 4.

### 265 3.3. Preliminary analysis and transformation of the field

266 To apply linear geostatistics under the most favorable hypotheses, it is convenient to  
267 obtain a marginal distribution of the field that is as Gaussian as possible. This property  
268 can be achieved through a suitable transformation of the original variable. Typically, for  
269 unimodal, positively skewed random variables the Box and Cox (1964) transformation  
270 represents a satisfactory solution. By means of a shape parameter  $\lambda$  the original field  
271  $Y(\mathbf{x})$  is transformed into a new, approximately Gaussian field:

$$Z(\mathbf{x}) = \begin{cases} \frac{Y(\mathbf{x})^\lambda - 1}{\lambda} & 0 < \lambda < 1 \\ \ln Y(\mathbf{x}) & \lambda = 0 \end{cases} \quad (12)$$

272 For a given set of data, an estimation of  $\lambda$  can be obtained by finding the value that makes  
273 the sample skewness the closest possible to zero.

274 In addition to its (approximate) Gaussian property, the field  $Z(\mathbf{x})$  obtained through the  
275 Box-Cox transformation also shows a more stable variance. If  $Y(\mathbf{x})$  is the field of a  
276 statistical parameter, it is then possible to attribute most of the variability of the variance  
277 of the sampling errors affecting  $Z_i^*$ , or the onsite estimations of  $Z(\mathbf{x}_i)$ , to the variable  
278 size of the recorded time series.

279 **4. Identification of spatial outliers in extreme rainfall data and their**  
280 **interpretation related to orographic effects**

281 Using the rainfall data for the study area described in Section 2, we now present an  
282 iterative statistical procedure to identify anomalous variability in the spatial field of the  
283 mean annual daily rainfall maxima. This procedure is based on the use of linear  
284 geostatistics. As such, it is quite general and can be easily exported to other regions. The  
285 comparison of statistically identified spatial outliers to objectively defined orographic  
286 barriers identified *a priori* of this analysis will provide new information and perhaps  
287 better insight into the variability of spatial characteristics associated with extreme rainfall.

288 *4.1. Preliminary data analysis and transformation*

289 A preliminary screening of the data highlights the presence of a positive skewness in the  
290 original annual maxima series. For short samples, this skewness would affect the  
291 Gaussian properties of the sample average. The Box-Cox transformation (Equation (12))  
292 was applied to address this issue. Looking at the graph in Figure 4, the natural logarithmic  
293 transformation is chosen ( $\lambda = 0$ ). A simple first order approximation of the mean of the  
294 transformed variable is the logarithm of the mean. This transformation was then used in  
295 the next geostatistical analysis.

296 At a regional scale, the transformed data show a negligible dependence on elevation (on  
297 average, 2% increment every 1000 m of elevation, Figure 5). This may not be true at a  
298 local scale; however, this preliminary step is only intended to assess if any global trends  
299 can be distinguished in order to de-trend the data and work on the residuals. In this case,  
300 there was no need for any further pre-treatment of the data.

301 The experimental semi-variogram of the log-transformed data shows a well-defined  
 302 structure, to which an exponential shape can be fitted (Figure 6a):

$$\gamma_Z(d) = n + s \cdot \left[ 1 - \exp\left(-\frac{3d}{r}\right) \right] \quad (13)$$

303 where parameters have the following values:

- 304 - nugget:  $n = 0.0160$ ;
- 305 - partial sill:  $s = 0.0539$ ;
- 306 - range:  $r = 122$  km.

307 The presence of a nugget in the experimental semi-variogram likely relates to a micro-  
 308 scale structure in the field or to the presence of noise in the data. In this case study, data  
 309 are known to be affected by a statistical error related to the estimation of the mean from  
 310 a finite sample. This error has a variance that depends on the length of each time series  
 311 and is therefore variable among sites. A first order approximated estimation (small  $\bar{c}_v$ )  
 312 of the sample variance  $\sigma_Z^2(x_i)$  of  $Z(\mathbf{x})$  at site  $i$  can be found using the following equation:

$$\hat{\sigma}_Z^2(x_i) = \frac{\bar{c}_v^2}{N_i} \quad i = 1, \dots, n \quad (14)$$

313 where  $\bar{c}_v$  is the regional average of the coefficient of variation of the original series of the  
 314 annual maxima and  $N_i$  is the length of the series at site  $i$ . Given the relatively large number  
 315 of gauged sites, each point of the experimental variogram is the average of a very large  
 316 number of pairs from the raw variogram. The effect of the noise on the experimental semi-  
 317 variogram, then, is a general increment as large as the average variance of the errors. The  
 318 quantitative assessment of the variance of the sampling errors allows us to separate the  
 319 nugget component produced by errors in the data from the remaining part caused by an  
 320 unknown micro-scale effect (see Table 2). A possible explanation of this ‘apparent’

321 micro-scale structure will be discussed later. The semi-variogram of the noiseless field is  
322 then obtained by subtracting the mean error variance from the entire experimental  
323 variogram.

#### 324 *4.2. Iterative statistical procedure for the identification of spatial outliers*

325 The presence of spatial outliers produced by the existence of an enhanced, small scale  
326 variability in the field actually contaminates the data-set and affects the estimation of the  
327 variogram. The identification of these anomalous values is based on the analysis of the  
328 residuals of a cross-validation procedure (Section 3.2). The KUD estimator was run for  
329 the jackknife estimation of the field at all sampling points and the standardized cross-  
330 validation residuals  $e_i^*$  defined in Equation (10) were calculated. These residuals do not  
331 show any correlation structure, although the observed variance is slightly smaller than 1  
332 (Figure 6b).

333 The introduction of sampling variance, which differs significantly from site to site, is  
334 mandatory in an application that tries to identify spatial outliers from standardized  
335 residuals. In this application, time series have a length that varies from 5 to 77 years; by  
336 using the Ordinary Kriging Predictor, the shorter series would automatically be more  
337 likely to produce anomalous errors.

338 The Normal Probability Chart in Figure 6c shows the standardized residuals obtained in  
339 the study region, along with their 95% confidence intervals and the line corresponding to  
340 the normal CDF, fitted through the 20<sup>th</sup> and the 80<sup>th</sup> percentiles. The overall shape of the  
341 empirical distribution shows little agreement with the normal straight line, especially at  
342 the upper tail, where an evident departure from the expected theoretical distribution is  
343 observed. The actual shape of the upper tail shows larger under-estimation errors than  
344 expected; those errors are then related to exceptionally high values of the data. These data

345 are considered spatial outliers when the expected probability of the standardized  
346 residuals, based on the normal distribution model, exceeds the limits of the confidence  
347 intervals in the plot. A possible explanation for the presence of spatial outliers in the data  
348 is the effect of rainfall amplification caused by orography.

349 As discussed previously, the presence of outliers in the data can affect the experimental  
350 semi-variogram and, consequently, the jackknife estimates. For this reason, the procedure  
351 must be iterated according to the following scheme:

- 352 1) a new sample without the anomalous values is obtained;
- 353 2) the new sample is used to estimate the experimental semi-variogram and to fit a  
354 theoretical model;
- 355 3) a new set of jackknife estimates is calculated by applying KUD to the whole  
356 dataset (previous outliers included);
- 357 4) a new set of anomalous values is identified;
- 358 5) if the outliers are the same as in the previous iteration, the procedure ends;  
359 otherwise, a new iteration is performed.

360 In this case study, three iterations were needed before the procedure was terminated. The  
361 final semi-variograms of the data (without outliers) and the standardized residuals, along  
362 with the Normal Probability Chart showing the set of spatial outliers and the final  
363 standardized residuals, are presented in Figure 7.

364 It is interesting to note how the nugget in the experimental semi-variogram in the last  
365 iteration is almost completely attributable to sampling errors. After subtracting the mean  
366 error variance, the nugget of the noiseless field is much lower than in the first iteration  
367 and very close to zero. This suggests that the hypothetical micro-scale structure was  
368 indeed an apparent one; it was likely one of the effects of the anomalous data contained

369 in the dataset on the semi-variogram. Once those data were removed, the experimental  
370 semi-variogram corresponded to an almost perfectly continuous noiseless field.

#### 371 *4.3. Validation of the iterative procedure*

372 To validate the accurate performance of the proposed iterative procedure, a reduced  
373 dataset without spatial outliers was tested using the same procedure. This verified whether  
374 the Gaussian properties of the standardized residuals remained. Both the variogram and  
375 the jackknife procedure were run on a set of data from which the spatial outliers were  
376 removed to check if the standardized residuals at the remaining sites were close to a  
377 standard normal distribution. Despite the appearance, the results of this validation are not  
378 obvious at all. In the previous section, it was implicitly assumed that the departure from  
379 the theoretical normal distribution of the standardized residuals was only caused by the  
380 presence of a few anomalous values in the data. Here, the aim is to check:

- 381 - if this assumption can be considered true; or if, aside from the spatial outliers,  
382 there is a more general departure from the hypotheses that support the application  
383 of linear geostatistics in the region; and
- 384 - if the iterative procedure is indeed able to find all spatial outliers in the data.

385 The experimental and fitted semi-variograms are the same as in the last iteration of the  
386 identification procedure. The residuals of the jackknife procedure were then calculated  
387 using non-outlying data only. The Normal Probability Chart shows a very good alignment  
388 of the standardized residuals along a straight line (Figure 8). In general, if after a few  
389 iterations validation has not occurred, a more comprehensive preliminary analysis of the  
390 homogeneity of the study region would be required.

391 On the one hand, this simple validation confirms the stationary and linear nature of the  
392 field when anomalous gauges are removed. On the other hand, it underlines the

393 importance of a properly designed monitoring network; if outliers had not been observed  
394 it would not have been possible to detect the phenomenon.

## 395 **5. Summary of the results and discussion**

396 The iterative procedure identified 19 anomalous gauges within the inner study region (the  
397 region of interest, where border effects should have less of an effect). These gauges are a  
398 small fraction of the total number of gauges (19 against 245); however, their effect on the  
399 geostatistical characterization of the field is anything but negligible (for example, the  
400 nugget in the experimental semi-variogram).

401 The basic statistics (Table 3) reveal that the average value of the field is much higher in  
402 the 19 anomalous gauges than in the other gauges of the region.

403 The presence of these spatial outliers should be investigated to better understand the cause  
404 of such high variability in the field recorded around those sites. More specifically, it  
405 would be interesting to assess whether the mean is affected by the presence of a few very  
406 intense events in the series or by a more general amplification of the events producing the  
407 annual maximum. The presence of outliers in the time series is well detected through the  
408 calculation of higher uneven order statistics (the skewness coefficient is used here).  
409 Skewness coefficients are reported in Table 3 for both anomalous and non-anomalous  
410 data. It is possible to see how similar the values are. The relatively higher value of the  
411 coefficient of variation for the anomalous stations is of particular interest. This value may  
412 just be the result of statistical errors in the estimation (for the anomalous subset, the  
413 coefficient is averaged over a small number of stations); nevertheless, if this is true, it  
414 may also result from an amplification effect that varies from event to event. This would  
415 increase the dispersion of the distribution of the annual maxima. Regardless, the increased

416 dispersion affects both the lower and the upper tail of the distribution almost equally, as  
417 the skewness coefficient suggests.

418 Another, perhaps more important question is whether it is possible to identify the physical  
419 factors that influence the rainfall field in such a way as to produce spatial outliers that are  
420 clearly evident in the mean annual maxima. In a climatologically homogeneous region  
421 like the one analyzed, orography is the geographic characteristic that affects the spatial  
422 variability of rainfall the most. This is confirmed by a preliminary examination of the  
423 results, as shown in Figure 9. When the anomalous gauges within the boundary of the  
424 inner study region (the region of interest) are represented on the orographic map, those  
425 stations are located very near orographic ridges. The problem is how this information can  
426 be formalized in an objective, reproducible and effective (for modeling) way. The results  
427 from Cuomo et al. (2011) were used to describe the orography of the region analyzed in  
428 this study.

429 When the spatial outliers are compared with the orographic objects of the 3<sup>rd</sup> and 4<sup>th</sup>  
430 orographic orders (ranges and groups), we find that most spatial outliers lie inside the  
431 perimeter of these objects (Figures 3 and 9).

432 A summary of rain gauge network characteristics is given in Table 4. Together, this table  
433 and Figure 9 reveal a lower network density exactly where it is more necessary: in areas  
434 with orographic features. This is a consequence of the historical inaccessibility of these  
435 places due to morphology, vegetation and a lack of infrastructure. The result is that the  
436 enhanced spatial variability of rainfall caused by orography not only is not properly  
437 observed, but it is even less observed than what a network with homogeneous average  
438 density would allow. Nevertheless, a consistent number of anomalous gauges have been  
439 found and the phenomenon has at least been detected.

440 The relative frequency of spatial anomalies within orographic boundaries is compared to  
441 the frequency of spatial anomalies outside orographic boundaries in Table 5. A direct,  
442 significant relationship between the geomorphologically identified boundaries and the  
443 presence of high spatial variability in the rainfall field is indicated. All of the statistics  
444 confirm this observation. Nearly 70% of the anomalous gauges are within the orographic  
445 boundaries, whereas only 20% of all the network gauges are in those areas. The frequency  
446 of occurrence of the outliers within the orographic boundaries is nearly 30%, while it is  
447 as little as 3% beyond those boundaries.

## 448 **6. Conclusions**

449 We analyzed the spatial variability of a low order statistic for series of annual daily  
450 rainfall maxima through an iterative statistical procedure that detected the presence of  
451 enhanced small scale variability in some areas of the region. By comparing the results of  
452 the statistical procedure to orographic objects independently identified using the  
453 geomorphological approach developed by Cuomo et al. (2011), we identified a  
454 convergence of orographic barriers that affect the spatial variability of extreme rainfall.  
455 These results open a new avenue of research that includes orographic effects in regional  
456 models of rainfall extremes, especially in areas where the morphology of orographic  
457 barriers is particularly complex. For example, in the case study addressed here, the  
458 characteristics of the objects represented by orographic ranges (4<sup>th</sup> order) and groups (3<sup>rd</sup>  
459 order) provide a foundation for the statistical modeling of the drift produced by  
460 orographic barriers and could lead to more accurate regional models for extreme rainfall.  
461 Moreover, the results of this work underline the need for a rain gauge network that can  
462 capture the higher spatial variability of rainfall induced by orographic obstacles. Our

463 preliminary results can provide the basis for defining better criteria for network designs  
464 and updates. A proper model of orographic effects on the spatial structure of a rainfall  
465 field would also better define the rules governing network updates; at the same time, a  
466 more accurate spatial sample of the rainfall field would allow improved detection of  
467 orographic effects and improve their modeling.

468 Both of these applications are under development for the region presented in this work  
469 and show promising preliminary results.

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